

Scheda Laboratori di Ricerca

<p>Denominazione del Laboratorio</p>	<p><i>Italiano</i> Laboratorio di Robotica <i>Inglese</i> Robotics Laboratory</p>
<p>Gruppo di Ricerca di Riferimento</p>	<p><i>Italiano</i> Robotica e Meccatronica <i>Inglese</i> Robotics and Mechatronics</p>
<p>Descrizione sintetica delle attrezzature, della strumentazione e delle attività di ricerca</p>	<p><i>Inglese</i> The research activities of the Vanvitelli Robotics Lab are mainly focused on:</p> <ul style="list-style-type: none"> • Motion and interaction control of robot manipulators • Planning and control of manipulation tasks based on multimodal sensing (vision, tactile, proximity, inertial) • Control of physical human-robot interaction • Development of innovative sensors for advanced robotic systems <p>Available Equipment</p> <ul style="list-style-type: none"> • Collaborative robot Kuka LBR iiwa • Collaborative robot Franka Emika Panda • Collaborative dual-arm system Universal Robot UR-5 • Industrial robot Yaskawa Motoman SIA5F • Industrial grippers Weiss Robotics WSG50 and WSG32 • 4 force/torque sensors (ATI and Robotous) • 4 RGB-D cameras • 1 thermographic camera Optris PI450 • 1 3D camera Viper Rubedos • 4 workstations i9 and i7 with GPU's (Titan V, RTX2080, GTX980)